

Linux multi-core scalability

Oct 2009

Andi Kleen
Intel Corporation
andi@firstfloor.org

Overview

- Scalability theory
- Linux history
- Some common scalability trouble-spots
- Application workarounds

Motivation

- CPUs still getting faster single-threaded
 - But more performance available by going parallel

- threaded CPUs dual-core quad-core hexa-core octo-core ...
 - 64-128 logical CPUs on standard machines upcoming
 - Cannot cheat on scalability anymore
 - High end machines larger
 - Rely on limited workloads for now

- Memory sizes are growing
 - Each CPU thread needs enough memory for its data (~1GB/thread)
 - Multi-core servers support a lot of memory (64-128GB)
 - Servers systems going towards TBs of RAM maximum
 - Large memory size is a scalability problem
 - Especially with 4K pages
 - Some known problems in older kernels ("split LRU")

Terminology

- Cores

- Core inside a CPU

- Threads (hardware)

- Multiple logical CPU per threaded core

- Sockets

- CPU package

- Nodes

- NUMA node with same memory latency

Systems

CPUs	Visible CPUs	Memory	Description
2 cores	2	2GB	Low end x86 desktop system 2008
4 cores x 2 threads x 2 sockets	8	4-8GB	Middle-end x86 desktop system 2009
4 cores x 2 threads x 2 sockets	16	8-32GB	Standard low end x86 server 2009
6 cores x 4 sockets	24	32-128GB	Standard 4 socket x86 server 2009
8 cores x 2 threads x 4 sockets	64	128-512GB	Standard 4 socket x86 server 2010
8 cores x 2 threads x 8 sockets	128	128GB-1TB	8 socket x86 server 2010
2 cores x 32 sockets	64	512GB-2TB	High end commercial server 2008
2 cores x 512 sockets	1024	>1TB	Super computer 2007

Table 1: Linux systems and their CPU numbers

Laws

- Amdahl's law:
 - Parallelization speedup limited by performance of serial part

- Amdahl assumes that data set size stays the same

- In practice we tend to be more guided by Gustafson's law
 - More cores/memory allow to process larger datasets
 - Easier more coarse grained parallelization

Parallelization classification

- Single job improvements
 - For example weather model
 - Parallelization of long running algorithm
 - Not covered here

- "Library style" / "server style" of tuning
 - Providing short lived operations for many parallel users
 - Typical for kernels, network servers, some databases (OLTP)
 - "requests" "syscalls" "transactions"
 - Key is to parallelize access to shared data structures
 - Let individual operations run independently
 - Usually no need to parallelize inside individual operations

Parallel data access tuning stages

Goal: Let threads run independent

- Code locking "first step"
 - One single lock per subsystem acquired by all code
 - Limits scaling
- Coarse grained data locking "lock data not code"
 - More locks: object locks, hash table lock
 - Reference counters to handle object lifetime
- Fine grained data locking (optional)
 - Even more locks (multiple per object)
 - Per bucket lock in a hash
- Fancy locking (only for critical paths)
 - Minimize communication (avoid false sharing)
 - per-CPU data
 - NUMA locality
 - Lock less: relying on ordered updates, Read-Copy-Update (RCU)

Communication latency

- For highly tuned parallel code often latency is the limiter
 - Time to bounce the lock/refcount cache line from core A to B
 - Cost depends on distance
 - Adds up with fine-grained locking
 - Physical limitations due to signal propagation delays
 - Solution is to localize data or do less locks

- Good news is that in the multi core future latencies are lower
 - Compared to traditional large MP systems

- Multi-core has very fast communication inside the chip
 - "shared caches"
 - Modern interconnects are faster, lower latency
 - But going off-chip is still very costly
 - Lower latencies tolerate more communication
 - Modern multi-core system of equivalent size is easier to program

Problems & Solutions

- Parallelization leads to more complexity, more bugs
 - Adds overhead for single thread
 - Better debugging tools to find problems
 - lockdep, tracing, kmemleak
- Locks, atomic operations add overhead
 - Atomic operations are slow and synchronization costs
 - Number of locks taken for simple syscalls high and growing
- Compile time options (for embedded), code patching
 - Problem: small multi-core vs large MP system
 - Still doesn't solve inherent complexity
- Lock less techniques (help scaling, but even more complex)
- Code patching for atomic operations

The locking cliff

- Still could fall off the locking cliff
 - Overhead of locking, complexity gets worse with more tuning
 - Can make further development difficult

- Sometimes solution is to not tune further
 - If use case is not important enough
 - Or speedup not large enough

- Or use new techniques
 - lock-less approaches
 - Radically new algorithms

□

Linux scalability history

- 2.0 big kernel lock for everything
- 2.2 big kernel lock for most of kernel, interrupts own locks
 - First usage on larger systems (16 CPUs)
- 2.4 more fine grained locking, still several common global locks
 - a lot of distributions back ported specific fixes
- 2.6 serious tuning, ongoing
 - New subsystems (multi queue scheduler, multi flow networking)
 - Very few big kernel lock users left
 - A few problematic locks like dcache, mm_sem
 - Advanced lock-less tuning (Read-Copy-Update, others)
- For more details see paper

Big Kernel Lock (BKL)

- Special lock that simulates old "explicit sleeping" semantics
 - Still some users left in 2.6.31
 - But usually not a serious problem (except on RT)

- File descriptor locking (flock et.al.)
- Some file systems (NFS, reiser)
- ioctls, some drivers, some VFS operations

- Not worth fixing for old drivers

VFS

- In general most IO is parallel
 - Depending on the file system, block driver

- namespace operations (dcache, icache) still have code locks
 - When creating path names for example
 - inode_lock / dcache_lock
 - Some fast paths in dcache (nearly) lock-less when nothing changes
 - Read only open faster
 - Still significant cache line bouncing
 - Can significantly limit scalability

- Effort under way to fine grain dcache/inode locking
 - Difficult because lock coverage is not clearly defined
 - Adds complexity

Memory management scaling

- In general scales well between processes
 - On older kernels make sure to have enough memory/core

- Coarse grained locking inside a process (struct mm_struct)
 - mm_sem semaphore to protect virtual memory mapping list
 - page_table_lock to protect page tables
 - Problems with parallel page faults, parallel brk/mmap

- mm_sem is a sleeping lock
 - Most page fault operations (including zeroing) hold
 - Convoying problems

- Problem for threaded HPC jobs, postgresql

Network scaling

- 1Gbit/s can be handled by single core on PC class
 - ... unless you use encryption
 - But 10Gbit/s still challenging

- Traditional single send queue, single receive queue per network card
 - Serializes sending, receiving

- Modern network cards support multi-queue
 - Multiple send (TX) queues to avoid contention while sending
 - Multiple receive (RX) queues to spread flows over CPUs

- Ongoing work in the network stack for better multi queue
 - RX spreading requires some manual tuning for now
 - Not supported in common production kernels (RHEL5)

Application workarounds I

- Scaling a non parallel program
 - Use Gustafson's law! Work on more data files
 - gcc: make -j\$(getconfig _NPROCESSORS_ONLN)
 - Requires proper Makefile dependencies
 - media encoder for more files:
 - find -name '*.foo' | xargs -n1 -P\$(getconf _NPROCESSORS_ONLN) encoder
 - Renderer:
 - render multiple pictures

- Multi threaded program that does not scale to system size
 - For example popular open source database
 - Limit parallelism to its scaling limit
 - Requires load tests to find out
 - Possibly run multiple instances

Application workarounds II

- Run multiple instances ("cluster in a box")
 - Can use containers or virtualization
 - Or just use multiple processes

- Run different programs on same system
 - "server consolidation"
 - Saves power and is easier to administrate
 - Often more reliable (but single point of failure too)

- Or keep cores idle until needed
 - Some spare capacity for peak loads is always a good idea
 - Not that costly with modern power saving

Conclusions

- Multi-core is hard

- Linux kernel is well prepared
 - but still some more work to do

- Application tuning is the biggest challenge
 - Is your application well prepared for multi-core?

- Standard toolbox of tuning techniques available

Resources

- Paper: <http://halobates.de/lk09-scalability.pdf>
 - Has more details in some areas

- Linux kernel source

- A lot of literature on parallelization available

- andi@firstfloor.org

Backup

Parallelization tuning cycle

- Measurement
 - Profilers: oprofile, lockstat
- Analysis
 - Identify locking, cache line bouncing hot spots
- Simple tuning
 - Move to next tuning stage
- Measure again
 - Stop or repeat with fancier tuning